1. Power Rails
   1. 24V batteries
   2. 12V DC
   3. 5V DC
   4. 220V AC
   5. PC power supply
2. Sensors
   1. Arm positions
   2. Wheel encoders (2 per)
   3. Kinect
   4. Sonars for reflexive halt?
   5. Sick LIDAR (?)
   6. ~~Hokuyo LIDAR (?)~~
   7. Gyro
   8. ~~Neato laser~~
   9. ~~GPS~~
3. Actuators
   1. Two wheels
   2. 6 DOF arm
   3. Gripper
4. Processing
   1. IRC5
   2. cRIO
   3. PC
5. COM/control
   1. E-stop
   2. Wifi bridge
   3. 360 Controller
   4. Warning Beacon Light